

Last time // overview - Gauss curvature of surfaces 2 things.

- distance function
 $B = \frac{1}{2} g^{-1} \Delta_x g$ shape operator of level sets

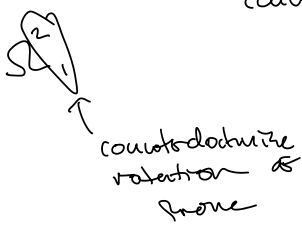
Fund eqn
 $\Delta_x B + B^2 = -R_x$

where $R_x(X) = -R(X, X)Z$
 why 2 minus? recall

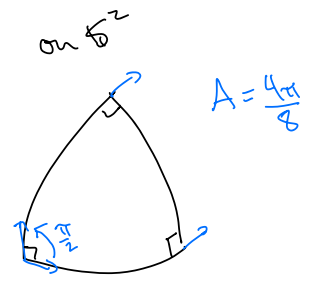
$$-\int_Q K dVol = \int_{\partial Q} \langle D\nu, e_2 \rangle A^2$$

$S^2_+(e_1, e_2)$ is the only natural ordering

counterclockwise
 Δ is rotation
 of an oriented
 frame, when
 traversed
 counterclockwise
 \uparrow orientation



uniformly, $-K$. To justify, K is d(rotation of parallel relative to frame)



So $\partial = e_1, X = e_2$

$$\langle X, R_x(X) \rangle = -\langle D\nu, e_2 \rangle \langle e_1, e_2 \rangle = K dVol(e_1, e_2)$$

Rank: $R_{abcd} = g_{ce} R_{abd}$ is very symmetric

obvious: R_{abcd}

2 legs obvious: R_{abcd}

↑ tensoriality \Rightarrow subject to check for on. from $\langle e_i, e_j \rangle$

A skew sym \Rightarrow
 $dA + A \wedge A$ skew-sym.

Alt. compute $(\partial_i \partial_j - \partial_j \partial_i)(e_i, e_j)$ ↓

even less

(\Leftrightarrow tors-free)

Prop (Poincaré) $R(x, y)z - R(z, y)x + R(y, z)x = 0$

↑ here, it's important we don't use a frame

$$\nabla_i \nabla_j \partial_k - \nabla_j \nabla_i \partial_k$$

6 permutations of (x, y, z)
 only 3 distinct

$\nabla_i \nabla_j \cdot : \Sigma_3 \rightarrow \mathbb{R}$ in group algebra

$$(1 - (12)) \nabla_i \nabla_j \cdot = R(\cdot, \cdot) \quad \Sigma_3 \subset \mathbb{R}(\Sigma_3) \text{ regular rep'n}$$

$$\mathbb{R} \langle \Sigma_3 \rangle$$

$$(1 + (123) + (123)^2)(1 - (12)) = \sum_{g \in \Sigma_3} \text{sgn}(g) g$$

$$= (1 + (123) + (123)^2)(1 - (23)) \quad \downarrow$$

Cor $R_{abcd} = R_{cdab}$

↑ Algebra on Σ_4

$$\mathbb{R}(\sigma(x, y, z, w)) : \Sigma_4 \rightarrow \mathbb{R}$$

$$\sigma = (123)$$

$$\tau = (1234)$$

$$(1 + (123) + (123)^2)R = 0$$

$$(1 + (12))R = 0$$

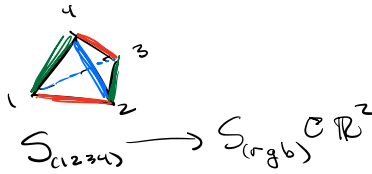
$$(1 + (34))R = 0$$

$$(1 + \tau + \tau^2 + \tau^3)(1 + \sigma + \sigma^2)$$

Representations of S^4

	<u>Spin</u>
<u>triv</u>	1
<u>alt</u>	1
<u>std</u>	3
<u>std\otimesalt</u>	3
<u>Fun</u>	2

rule out • triv by $1 + (12) = 2$
 Friendly \rightarrow • alt by $1 + \sigma + \sigma^2 = 3$ distinct
 (just rules this out)
 • std by $(12)(34) = \begin{pmatrix} 1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix}$
 + 4d alt by $(12)(34) = \begin{pmatrix} 1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix}$



Also useful

2nd Friedri.

$$d^2 \Omega = 0$$

True in general, but there's a trick for \mathbb{R}

$$\begin{aligned} d(dA + \frac{1}{2}[A, A]) &= [A, dA + \frac{1}{2}[A, A]] \\ &= \frac{1}{2}[dA, A] - \frac{1}{2}[A, dA] + [A, dA] + \frac{1}{2}[A, [A, A]] \end{aligned}$$

$\underbrace{\hspace{10em}}_0$
 \uparrow
Jacobi's

Normal coordinate trick:

- Metric in normal coords

$$\begin{aligned} \ddot{x}^i + \Gamma_{jk}^i \dot{x}^j \dot{x}^k &= 0 \Rightarrow \Gamma_{ijk} = 0 \\ &\Rightarrow \Gamma = 0 \\ &\Rightarrow g_{ij} = \delta_{ij} + O(k^2) \end{aligned}$$

Use normal coords when you can to drop terms!

$$\begin{aligned} \nabla_a \nabla_b \nabla_c \partial_d - \nabla_b \nabla_a \nabla_c \partial_d &= R(a,b)(\nabla \partial_d) = 0 \\ \Rightarrow (1 - (123) - (123)^2) \nabla_a \nabla_b \partial_d &= 0 \end{aligned}$$

Think $(n, V) = \mathbb{R}^{\{\text{sym}\{a,b,c,d\}, (1,2;3,4)\}}$,
 the \mathfrak{so}_2 -isotypic part is a dual

$$\Sigma_4 \subset V \hookrightarrow \{\text{Sym}\{a,b,c,d\}\}$$

More fundamentally, $\Sigma_4 \otimes^4 \mathbb{T}M \hookrightarrow \text{GL}(M)$
 $\downarrow \mathbb{R}$
 \mathbb{R}

\mathfrak{so}_2 -part is an irred $\text{GL}(M)$ rep but still many inequivalent line reps on it.

Alternative perspective

$\cdot \mathcal{R} : \Lambda^2 \mathbb{T}M \rightarrow \Lambda^2 \mathbb{T}M$ self-adjoint s.t. \mathcal{R} orthogonal to $\Lambda^2 \mathbb{T}M$

(this is the twisted GL-rep)

$$\ker(\mathcal{R}) \perp \mathbb{R}$$

Plicker \sim exactly cuts out the simple tensors.

Sectional curvatures

For surfaces M^2

$T_x^{\text{form}} TM$ is 1-dimensional
(R_{1212} determines all)

If $M \rightarrow \mathbb{R}^3$, it's $\det(h_{ab})$

$$\begin{aligned} \text{check } S &= g^{ab} R_{cab}{}^c \\ &= R_{12}{}^1{}_2 + R_{21}{}^2{}_1 = 2K \end{aligned}$$

Return to general n :

If $\Pi \in T_p M$ is a 2-plane, define

$$S_\Pi = \exp_p(\Pi) \in M$$

$$\text{sec}(\Pi) = K_p(S_\Pi).$$

"
sec(v, w)

$$\text{Prop } \text{sec}(v, w) = \frac{v^a w^b v^c w^d R_{abcd}}{|v \wedge w|^2}$$

$\Gamma \Pi = 0$ at p

$$\Rightarrow R|_{TS_\Pi} = \tilde{R}|_{TS_\Pi} \text{ at } p$$

If (v, w) orthonormal, we are done

else check effect of $\begin{pmatrix} av+bw \\ cw-dw \end{pmatrix}$.

i.e. quadratic form determined up to $\mathbb{R}^4 V$ by
restriction to simple tensors in $\mathbb{R}^2 V$

↓

Prop ^{All} The sectional curvatures determine R .

Let $D = R^{(1)} - R^{(2)}$.

$$0 = D(v-w, x, v-w, x) \\ = 2D(v, x, w, x)$$

$$0 = D(v, x+u, w, x+u) \\ = D(v, x, w, u) + D(v, u, w, x)$$

gives extra relation, makes it 0

Prop $R_c(v, v) = \sum_{e_i} R(e_i, v, e_i, v)$ For an orthonormal basis $e_i \perp v$

$$= |v|^2 \sum_{e_i} \sec(e_i, \frac{v}{|v|})$$

$$S = \sum_{i \neq j} D(e_i, e_j, e_i, e_j) \\ = 2 \sum_{i < j} \sec(e_i, e_j)$$

Cor \sec always $\geq 0 \Rightarrow Ric, S$ always ≥ 0
 ≤ 0

In particular, constant sectional curvature $K \iff$

$$R_{abcd} = K (g_{ac}g_{bd} - g_{ad}g_{bc})$$

wait — is this Pizardini?

Defn $g_{ac}g_{bd} - g_{ad}g_{bc}$ not Pizardini, but
 maybe is when
 you skew-symmetrize.